Graph fundamentals

Paolo Boldi DSI LAW (Laboratory for Web Algorithmics) Università degli Studi di Milan

- Graphs appear everywhere: they are an extremely useful formalism!
- Unfortunately: nomenclature and notation is not enough standardized
- The purpose of this lesson is
 - establishing the notation we shall be using in the future
 - singling out some properties that will be of help
 - providing some algorithmic highlight on graphs

- A graph G = (N_G, A_G) is defined by a finite set of nodes N_G and by a set of arcs A_G ⊆ N_G × N_G
- ▶ The subscript *G* is omitted when clear from the context
- This is sometimes called "network", or "directed graph" or "digraph": I will add the adjective *directed* only when doubts can arise
- Usually $n_G = |N_G|$ and $m_G = |A_G|$. Of course $0 \le m_G \le n_G^2$.

Graph representation

- It is customary to represent graphically a graph, depicting every node with a small circle and every arc (x, y) as a directed arrow from x to y.
- Observe that there is no commitment as to where nodes should be placed (the *embedding* used) or how arcs should be drawn.



 Drawing graphs "nicely" is by itself an important part of graph theory.



- An arc (x, y) is said to start (or stem) from x and to end on y; x is its source and y is its target
- We say that (x, y) is incident on x and y.
- ▶ y is a *successor* (or *out-neighbor*) of x
- x is a predecessor (or in-neighbor) of y



- An arc of the form (x, x) is called a (self-)loop; graphs without loops are called loopless (and may have at most n(n − 1) arcs).
- ► Two arcs of the form (x, y) and (y, x) are called reciprocal of each other
- IMPORTANT: it is impossible to have two parallel arcs with the same source and target (if you need them, you should resort to "multigraphs")

Transpose graphs

- ▶ Given a graph *G*, define its *transpose* as $G^T = (N_G, A_G^T)$ where $A_G^T = \{(y, x) \mid (x, y) \in A_G\}$.
- Example:



- A graph is G symmetric iff G = G^T. In symmetric graphs, arcs come in pairs: every arc (x, y) correspond to an arc (y, x).
- ► The pair of arcs {(x, y), (y, x)} is called an *edge* and may be thought of as a *set of (at most) two nodes* {x, y}.
- This is how most people define undirected graphs: we shall actually consider the latter as a synonym of "symmetric (loopless)".



- Edges of an undirected graph can be thought of as elements of ^V
 ₂
 ₂
- ► In undirected graphs, nodes are often called *vertices*.
- Notational problem: should m_G denote the number of arcs or the number of edges? I prefer to stick to arcs, and reserve e_G for the number of edges (that is m_G/2, in the loopless case)

- We let N⁺_G(x) be the set of out-neighbors of x; its cardinality, d⁺(x), is called the *out-degree* of x
- We let N[−]_G(x) be the set of in-neighbors of x; its cardinality, d[−](x), is called the *in-degree* of x
- For undirected graphs, we use $N_G(x)$ and $d_G(x)$

- In a graph G a path is a sequence of nodes π = ⟨x₀, x₁,..., x_ℓ⟩ such that (x_{i-1}, x_i) ∈ A_G for all i = 1,..., ℓ
- $|\pi| = \ell$ is called the *length* of π
- π is called *simple* iff nodes are all distinct
- We say that π starts from x_0 and ends in x_ℓ , and write $\pi : x_0 \rightsquigarrow x_\ell$
- We say that x_ℓ is reachable from x₀ iff there is a path from x₀ to x_ℓ

- ▶ In a graph *G*, a *cycle* is a nonempty path of length that starts and ends in the same node.
- It is simple if no node (except for the starting/ending one) is repeated.
- A graph is *acyclic* iff it contains no simple cycle.
- ► For undirected graph, the request is that a cycle be of length ≥ 3.

Connected components

- For a given graph G, the relation →→ (reachability) is a pre-order: it is reflexive and transitive.
- Its associated equivalence relation x ~ y is defined by x → y and y → x.
- The equivalence classes of ~ are called the (strongly) connected components of the graph.
- \blacktriangleright \rightsquigarrow is a partial order on the components (hence: it is acyclic).



Connected components

In an undirected graph, there are no edges between different components!





- A general technique that is used to do "something" with the nodes of a graph
- Traversals consider all the nodes of the graph exactly once, in some order
- The order depends on the kind of visit
- At any moment, all nodes are classified into:
 - unknown (white)
 - frontier: known but unvisited (grey)
 - visited (black)

- all nodes are initially white
- the frontier is empty

init(): Initialization $St[-] \leftarrow$ white $F \leftarrow \emptyset$

Visit: 2) cycle

- provided that some nodes are used as seed...
- ...i.e., initially set as grey put in the frontier

```
visit(): Perform a visit cycle
while F \neq \emptyset do
  x \leftarrow F.pick()
  visit(x)
  St[x] \leftarrow black
  for v \in N^+(x) do
     if S[y] = white then
        St[y] \leftarrow grey
        F.add(y)
     end if
  end for
end while
```

- performs a visit starting from the first white nodes
- at the end, all nodes are black

```
init()
for x \in N do
if St[x] = white then
for x \in S do
St[x] \leftarrow grey
F.add(x)
end for
visit()
end if
end for
```

The type of traversal changes depending on the data structure used for the frontier (i.e., implementation of the *pick* method).

- ▶ If *F* is a *stack* (LIFO), the visit is a *depth-first search* (DFS)
- ▶ If *F* is a *queue* (FIFO), the visit is a *breadth-first search* (BFS)
- Note: DFS can also be implemented with an implicit stack, using recursion.

Finding shortest paths (in unweighted graphs) from a given source s.

- Perform a BFS from *s*.
- When a node enters the frontier, the node under visit is marked as his *parent*: it is the next-to-last node in a shortest path from s.
- Works perfectly even for directed graphs.

An example of application is finding the connected components of an *undirected graph*

- Each single visit touches all (and only) the nodes of a single component
- In this case, the visit order is irrelevant: any frontier datastructure will do the job!

The most trivial representation of a graph is its adjacency matrix:

(0	0	1	1	0	
	1	0	0	1	1	
	0	1	1	0	0	
	0	0	0	0	0	
ĺ	1	1	0	1	0)

- ▶ Requires n² bits: very expensive for sparse graphs (i.e., when m ≪ n²)
- Obtaining the successors of a node requires time O(n)
- Knowing if (x, y) is an arc requires time O(1)

Alternatively, one can use *adjacency lists*:

$$\begin{array}{rcl} L[0] &=& \langle 2,3\rangle \\ L[1] &=& \langle 0,3,4\rangle \\ L[2] &=& \langle 1,2\rangle \\ L[3] &=& \langle \rangle \\ L[4] &=& \langle 0,1,3\rangle \end{array}$$

- Requires m log n bits, plus the space for the offsets of every list
- Obtaining the successors of node x requires time O(|N⁺(x)|) (amortized constant)
- Knowing if (x, y) is an arc requires time O(|N⁺(x)|) (maximum degree, in the worst case, or n)